

Hydrophobic Effects and Acoustic Wave Response

Glen McHale

Nottingham Trent University
Nottingham NG11 8NS, UK

Overview

1. Ideas

- Contact angles and cavity lengths
- Molecular slip
- Surface structure
- Diffuse boundaries

2. Models & Interpretations

- Effective acoustic interface
- Sauerbrey “liquid mass”
- Acoustic reflections

3. Experiments & Results

- QCR surfaces with pillars
- Pillars and hydrophobicity

Hydrophobic Effects

Key Ideas

Liquids Response and Modelling

Shear Mode Vibration

Entrains liquid

Liquid oscillation decays

Penetration depth

$$\delta = (\eta / \pi f \rho)^{1/2}$$

Modelling

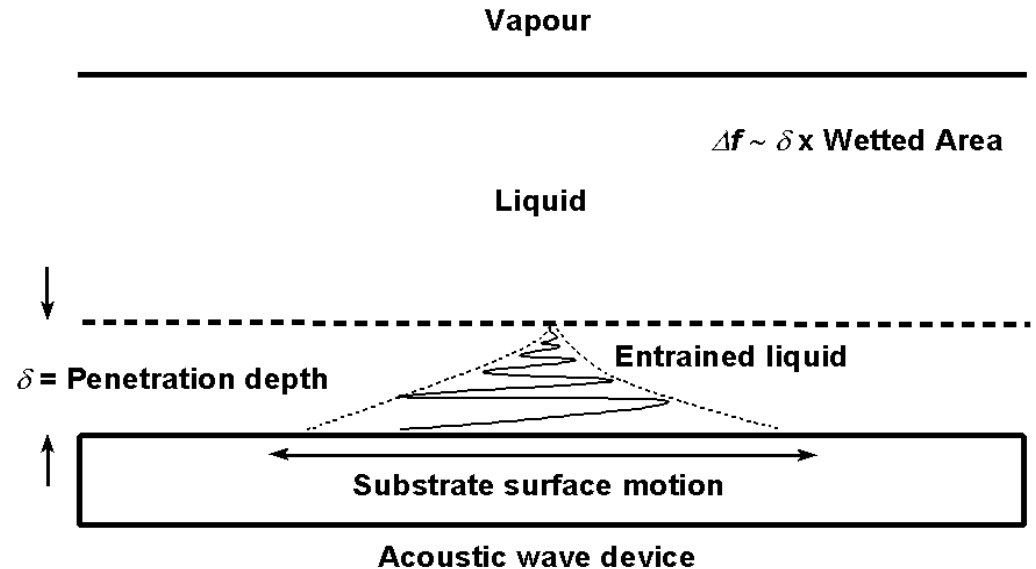
Navier-stokes equations in liquid (or equivalent ones if a polymer)

Wave equations in solid

Vanishing stress at liquid surface

Match speeds at solid-liquid boundary

→ Kanazawa-Gordon &
Sauerbrey/Polymer Models



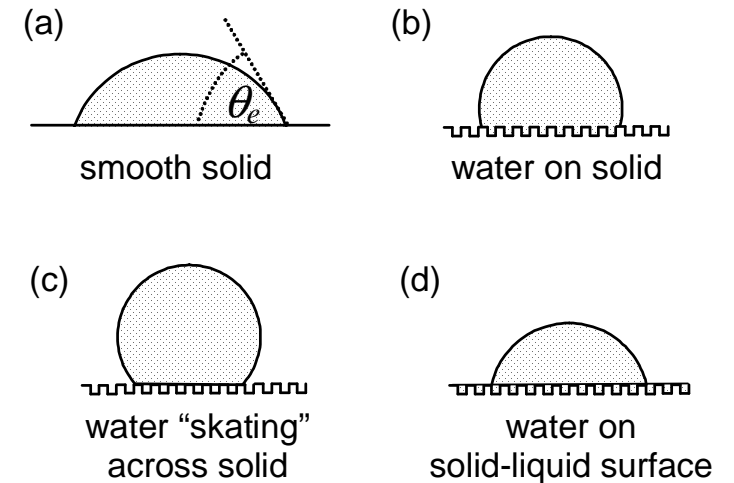
*Assumes i) matching of speeds at physical location of boundary
and ii) uniform solid-liquid boundary*

Contact Angles and Cavity Lengths

Contact Angle

Indicates relative interfacial energies

Ability to penetrate surface features



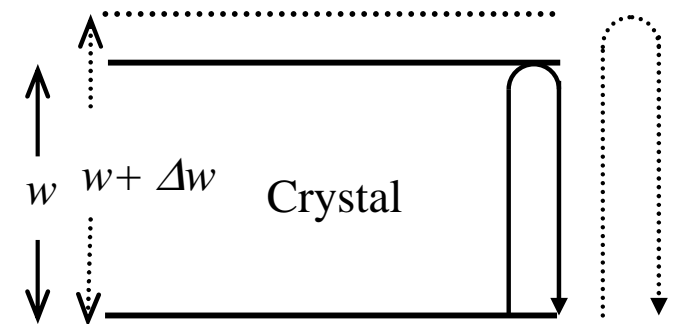
Resonant Cavity

QCM as standing wave cavity with $\square w = \lambda/2$

Added mass moves effective boundary

Added liquid moves effective boundary by \sim penetration depth

Sauerbrey and Kanazawa-Gordon Eqns follow



Effective cavity smaller \Rightarrow higher frequency

Effective cavity larger \Rightarrow lower frequency

Potential Problems 1 – Molecular Slip

Molecular Slip

Surface mobility is different to bulk

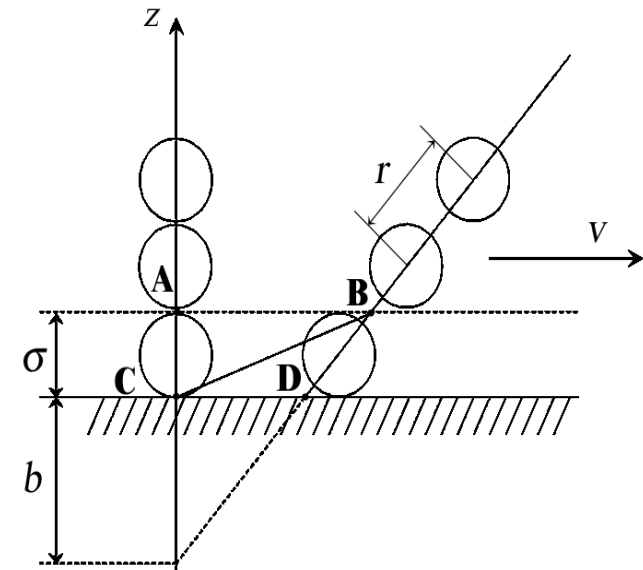
Blake-Tolstoi theory

Surface-to-bulk mobility

$$\frac{u_s}{u} = \exp\left[\alpha A \gamma^{LV} (1 - \cos \theta) / kT\right]$$

Dependence on contact angle

Slip length b



$$b = r \left(\exp\left[\alpha A \gamma^{LV} (1 - \cos \theta) / kT\right] - 1 \right)$$

Wetting Case $\theta=0^\circ$

Bulk and surface mobility's identical

Slip length vanishes

Friction coefficient $k=\eta_f/b$ infinite

Non-Wetting Case $\theta=180^\circ$

Surface mobility exponentially large

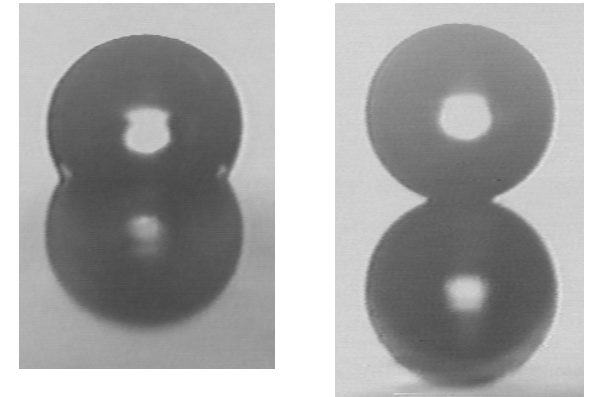
Slip length exists

Friction coefficient $k=\eta_f/b$ reduces

Potential Problems 2 – Surface Structure

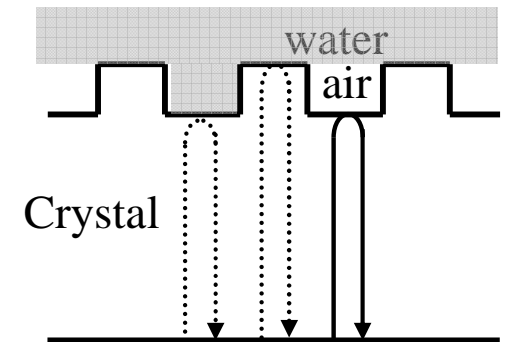
Capillary Penetration

Liquid skates across solid surface
Same hydrophobicity
Different surface structure
Super-hydrophobic effect



Laterally Dependent Acoustic Reflectivity

Multiple cavity lengths
Varying strength of reflection
Change in position of effective acoustic interface



Wetting Case $\theta=0^\circ$

Reflectivity's at all places equivalent
Effective cavity length is an average
Defines slip length $b=0$

Non-Wetting Case $\theta=180^\circ$

Incomplete liquid penetration
Reflectivity changes effective cavity
Slip length b exists

Potential Problems 3 – Diffuse Boundary

Hard Solid-Liquid Interface

Boundary is well-defined so no problems

Examples: QCM as film thickness monitor in vacuum chamber
 QCM as viscosity-density sensor in Newtonian liquid
 QCM for mass deposition in liquid

Soft Boundary

“Dressed surface”

Example: Surfaces with anchored chains
 Vesicles - “Bags of water” in water

Porous-Hard Boundary

Example: Super-fluid resonator cavity with sintered boundary linings

Issue: Effective acoustic interface versus physical boundary

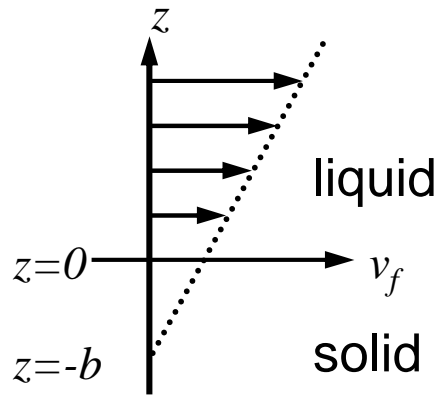
Hydrophobic Effects

Models & Interpretations

Mathematical Formulation of Wall Slip

Flow Profile

With Slip length



Slip length, b , models effective position of interface
Negative b , effective interface moves to liquid side
of boundary

Equations

Match speeds

$$v_s(z=0) = v_f(z=-b)$$

Expand

$$v_w - v_f(z=0) = -b \left(\frac{\partial v_f}{\partial z} \right)_{z=0}$$

Force exerted on wall
divided by viscosity

Slip Length

Mechanism for modelling an effective average boundary
and/or taking into account liquid-solid interfacial forces

Slip and Effective Sauerbrey “Liquid Mass”

Equations of Motion

Solve with slip boundary condition¹

Consider in terms of slip length² and interpret solution for small b

Newtonian Liquid

Kanazawa & Gordon result for no-slip modified by “slip” correction using b/δ

$$\left(\frac{\Delta\omega}{\omega}\right)_{slip} \approx \left(\frac{\Delta\omega}{\omega}\right)_{no\ slip} \left(1 - \frac{2b}{\delta}\right)$$

Slip length to penetration depth ratio

Negative Slip Length

Define a liquid mass as $\Delta m_f = b\rho_f$

$$\left(\frac{\Delta\omega}{\omega}\right)_{additional} \approx \left(-\frac{2b}{\delta}\right) \left(\frac{\Delta\omega}{\omega}\right)_{no\ slip} = \frac{\omega\Delta m_f}{\pi\sqrt{\mu_s\rho_s}}$$

Sauerbrey result for additional trapped “rigid liquid mass”

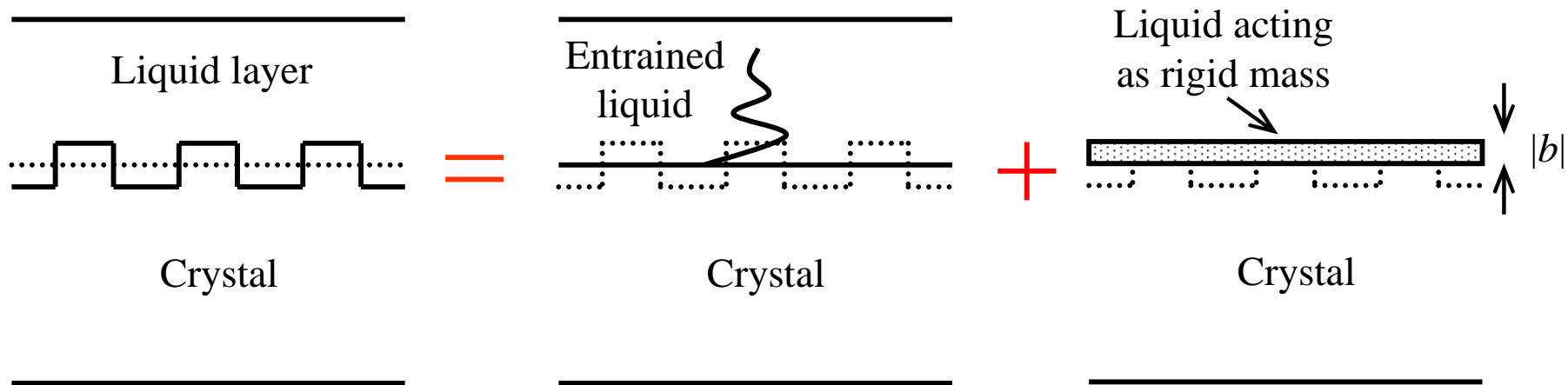
¹G. McHale, R. Lücklum, M.I. Newton, *et al.*, J APPL PHYS 88, 7304-7312 (2000)

²G. McHale & M.I. Newton, J APPL PHYS 95 373-380 (2004)

Pictorial Interpretation

Negative Slip Length

slip boundary condition = no-slip boundary condition + rigid “water” mass layer
(Kanazawa liquid response) (Sauerbrey “liquid mass” response)



Acoustic Reflection View

Substrate Supports Standing Waves



Cavity length increases \Rightarrow additional frequency decrease

Limitations on “Slip” B.C./Trapped Mass View

Effectively assuming equal reflectivity at peaks and troughs of topography

Cannot necessarily use additivity of liquid entrainment + trapped mass when incomplete liquid penetration occurs

Hydrophobic Effects

Experiments & Results

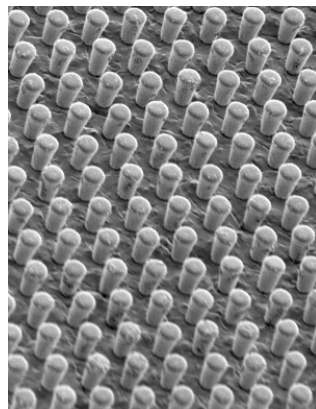
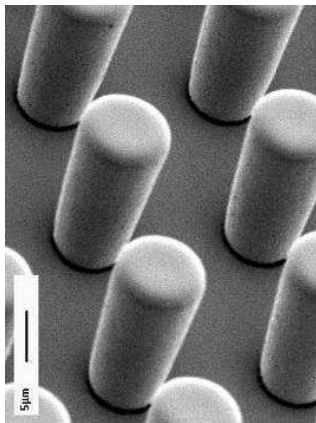
Super-Hydrophobic Crystals

Patterned Crystals

SU-8 patterns on 5 MHz quartz crystals

Pillars of 5 μm diameter, 10 μm cnt-cnt

Heights of 3 μm to 10 μm

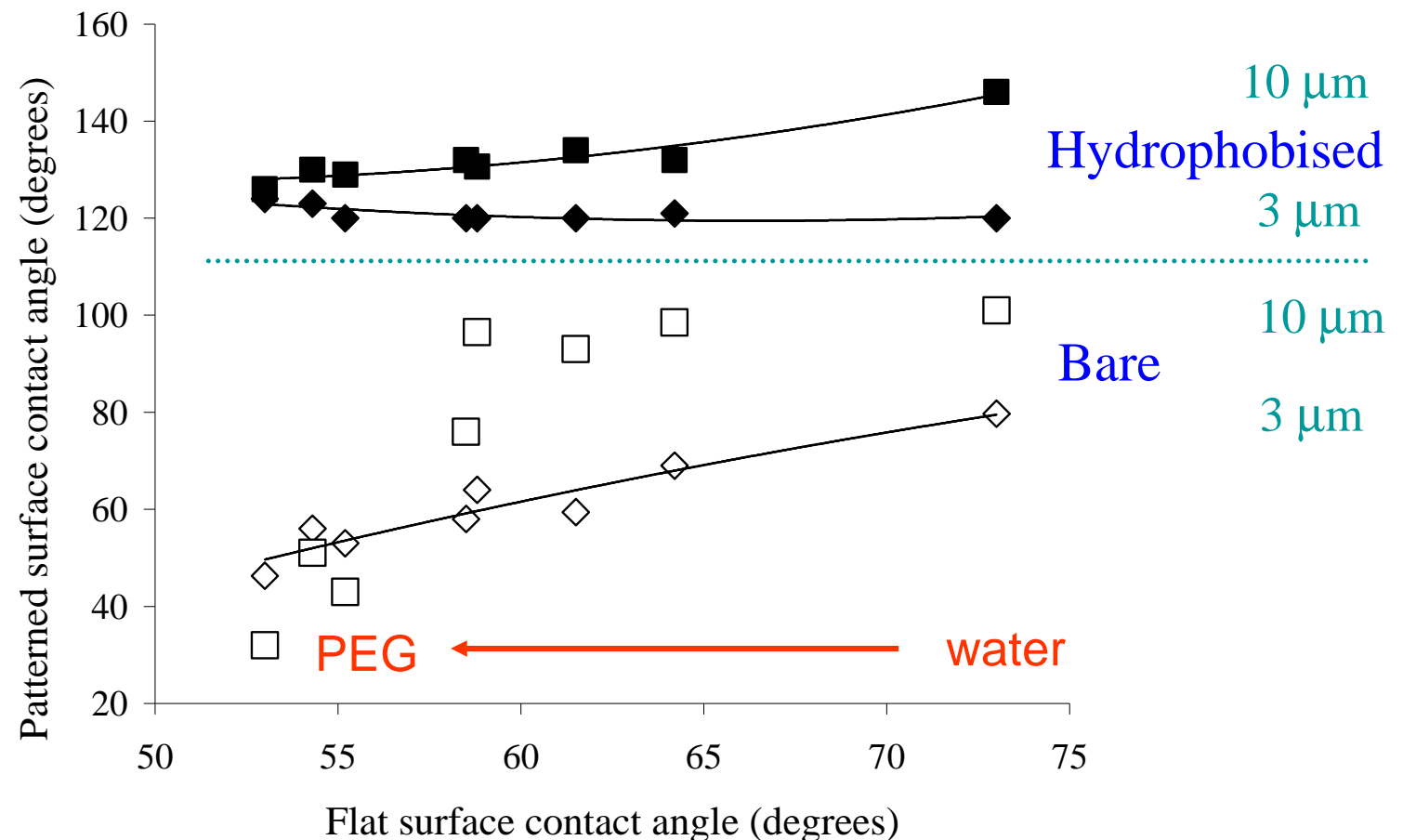


Preliminary Experiments

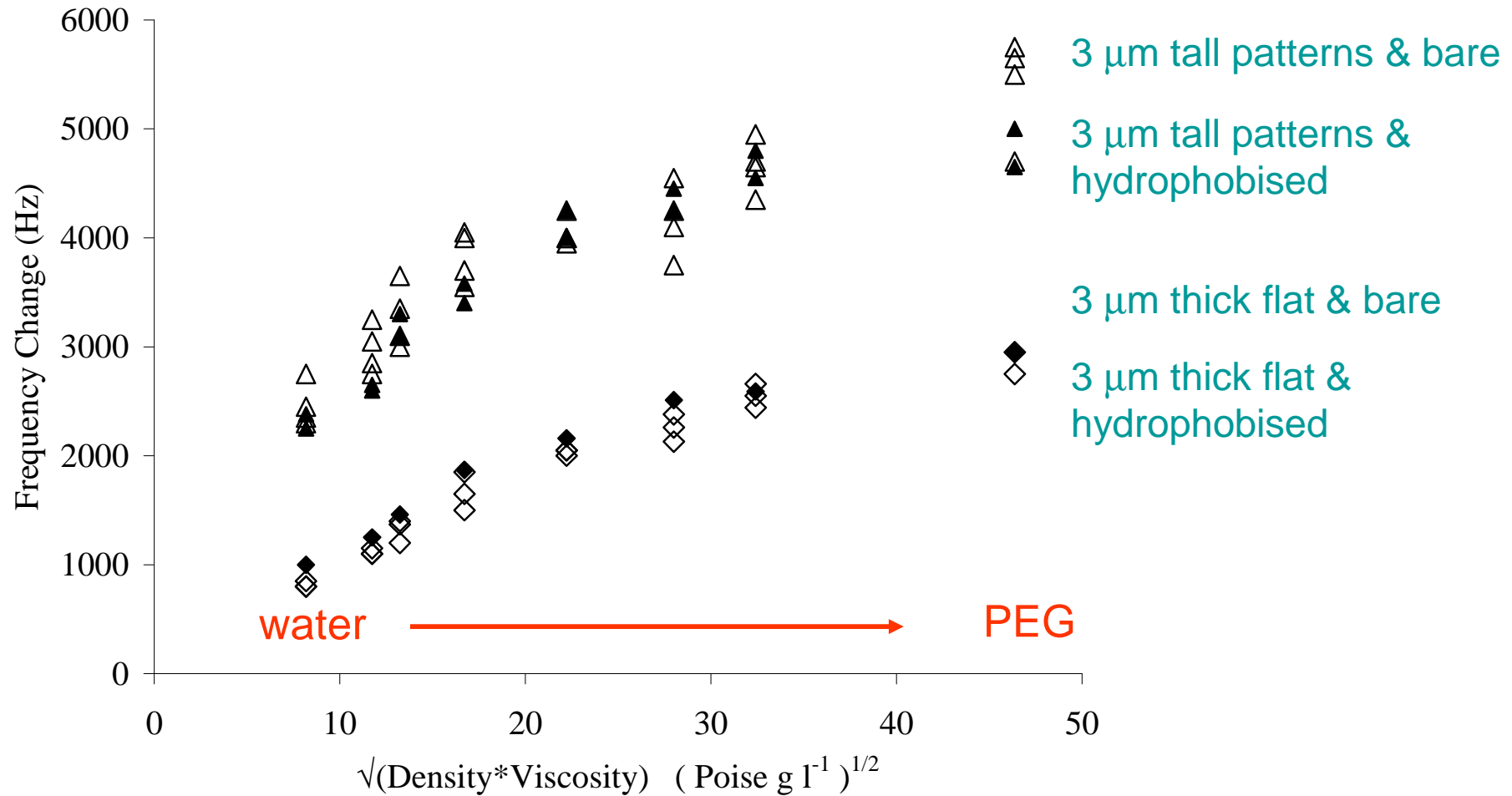
Flat and patterned layers

Bare (70-80°) & hydrophobised (110-120°)

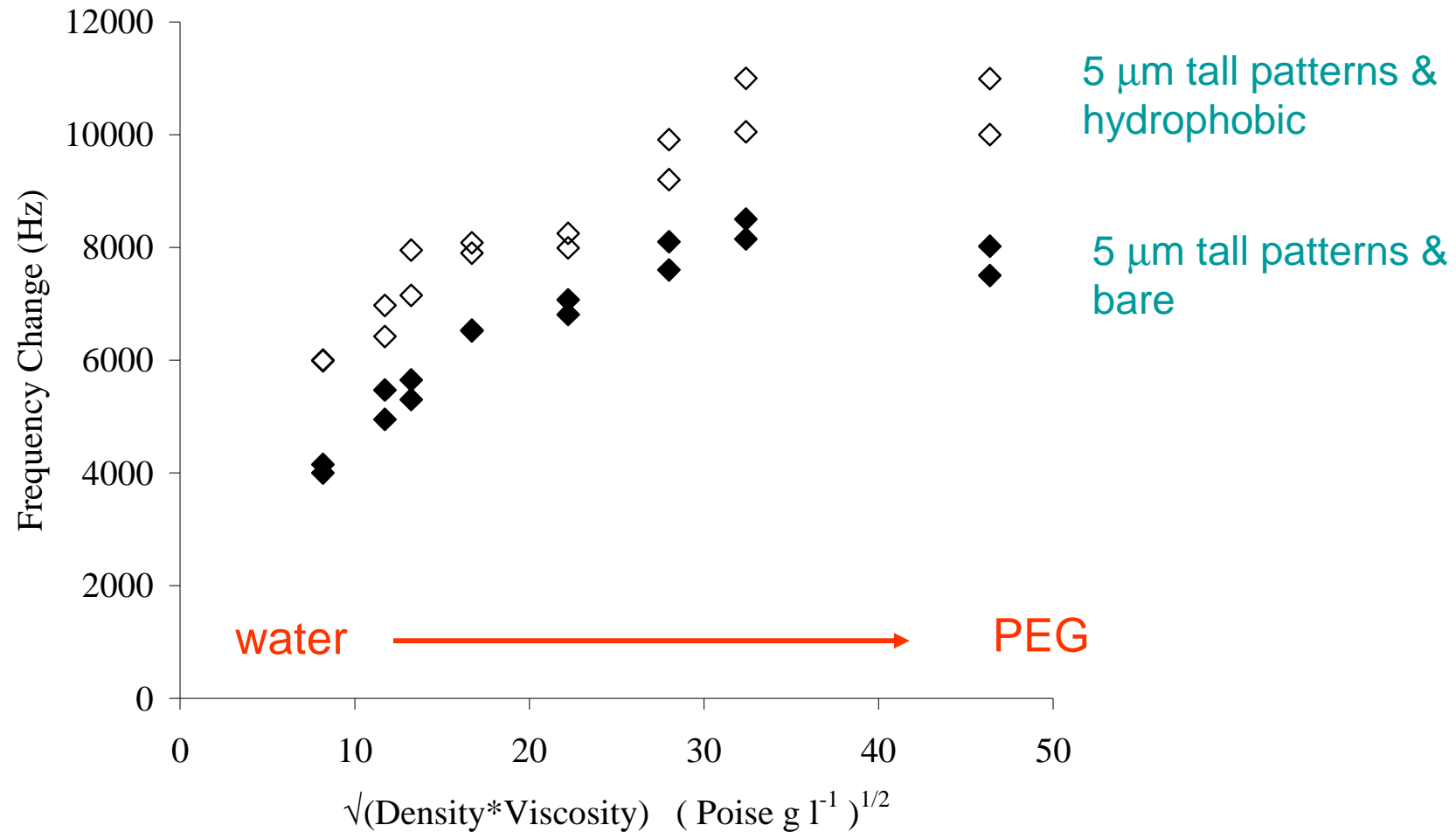
3350 MW PEG solutions 678-20000 mPa s



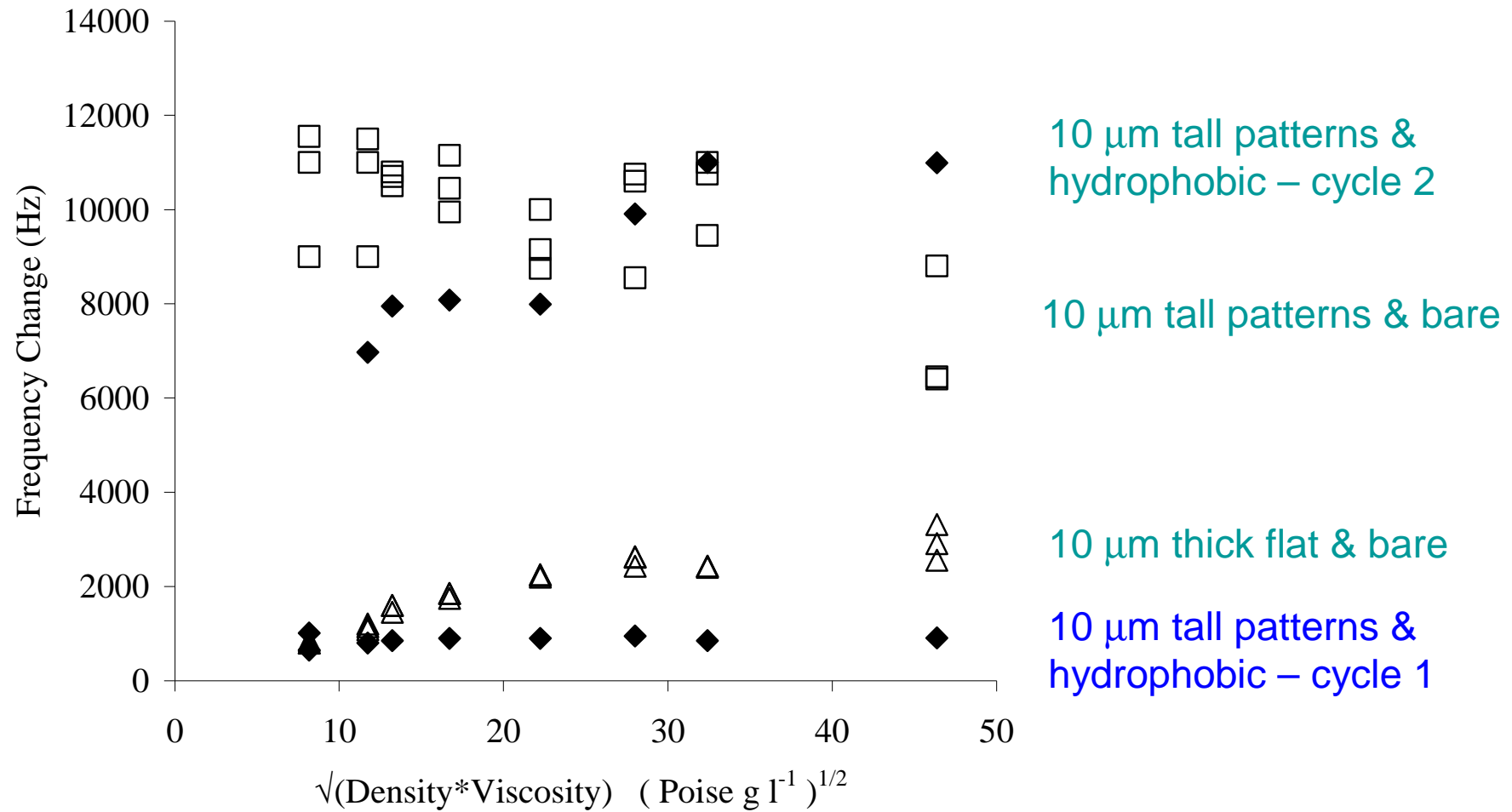
Low Pillar Height QCR Frequency Decrease



Medium Pillar Height Hydrophobic Dependence



Tall Pillar Height Hydrophobic Dependence



water → PEG

Acknowledgements

- Mike Thompson, Gordon Hayward and Jon Ellis
Wetting/Super-hydrophobic QCM, slip and diffuse interface concepts
Matching slip length to slip parameter in boundary condition
- Richard Cernosek and Lisa Thiesen
Air trapping and wetting
- Ralf Lücklum
Slip parameter in boundary condition and wetting concepts
- Mike Newton, Carl Evans and Neil Shirtcliffe
Super-hydrophobicity

Key References

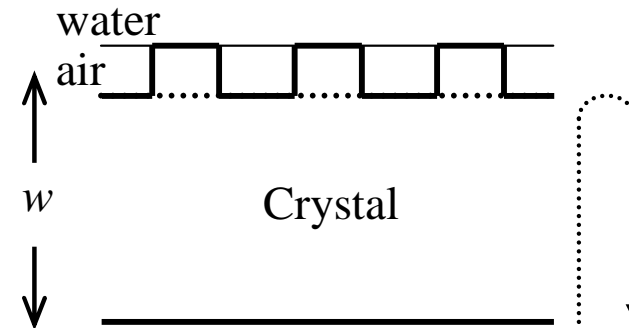
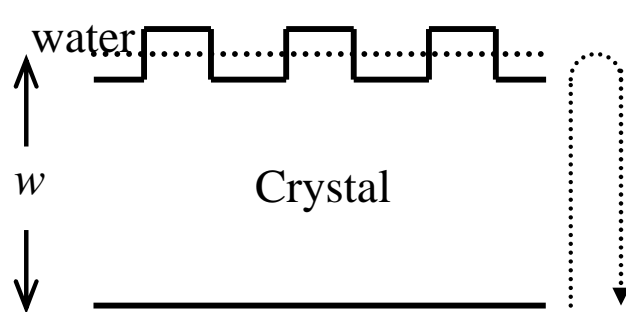
- G. McHale & M.I. Newton, *Surface roughness and interfacial slip boundary condition for quartz crystal microbalances*, J APPL PHYS 95 373-380 (2004)
- J.S. Ellis, G. McHale, G.L. Hayward & M. Thompson, *Contact angle-based predictive model for slip at the solid-liquid interface of a transverse-shear mode acoustic wave device*, J APPL PHYS 94 6201-6207 (2003)
- G. McHale, R. Lücklum, M.I. Newton, *et al.*, *Influence of viscoelasticity and interfacial slip on acoustic wave sensors*, J APPL PHYS 88, 7304-7312 (2000)

The End

Order of Magnitude Estimates – QCMs

Is Positive Δf Possible?

Possibly, if **effective cavity length decreases** due to changes in reflectivity
Incomplete liquid penetration versus liquid penetration?



Effective QCM Cavity Lengths, w

$$v = f\lambda \Rightarrow \Delta w/w = -\Delta f/f$$

(v approx constant)

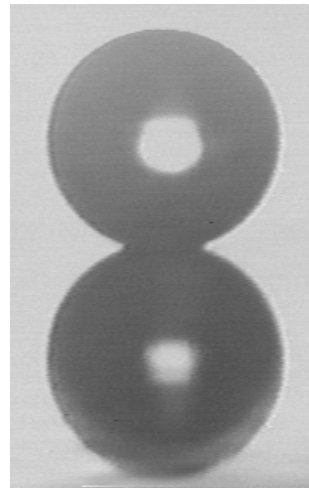
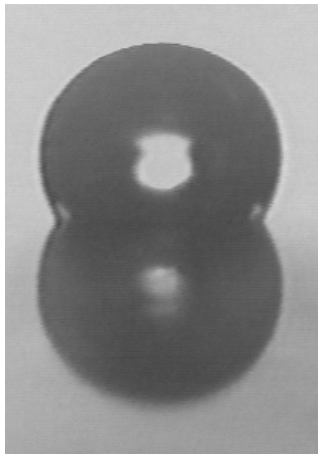
$f = 5 \text{ MHz}$ and $w = 330 \text{ }\mu\text{m}$

Δw	$ \Delta f $
100 Å	150 Hz
100 nm	1.5 kHz
1 μm	15 kHz
10 μm	150 kHz

Super-Hydrophobic Surfaces

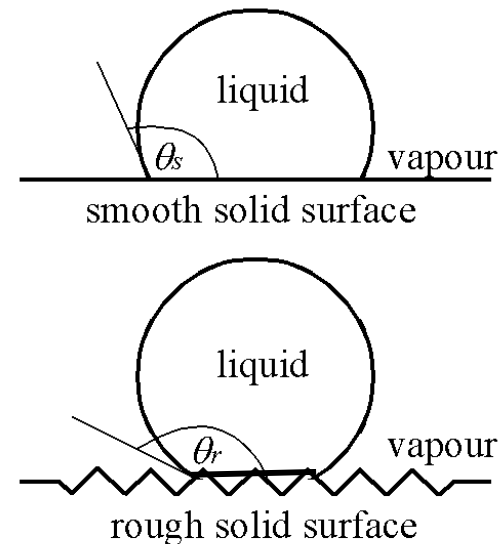
Contact Angle

Side view images of droplet
Identical chemical functionality
Different topography



Physical Cause

Surface roughness/ topography
Incomplete liquid penetration (or)
Greater solid-liquid interfacial area



New Sensor Principle

Change hydrophobicity to cause super-hydrophobic transition
Response of QCM/SAW may alter by far more than due to mass change